

Formula Sheet: Richard L. Smith

$$\begin{pmatrix} Y \\ Y_0 \end{pmatrix} \sim N \left[\begin{pmatrix} X\beta \\ x_0^T\beta \end{pmatrix}, \begin{pmatrix} V & w^T \\ w & v_0 \end{pmatrix} \right]$$

where Y is an n -dimensional vector of observations, Y_0 is some unobserved quantity we want to predict, X and x_0 are known regressors, and β is a p -dimensional regression coefficient vector.

REML Estimation: $\hat{\beta}$ by GLS regression, $\hat{\theta}$ chosen to maximize

$$\ell_n(\theta) = -\frac{1}{2} \log |V(\theta)| - \frac{1}{2} \log |X^T V(\theta)^{-1} X| - \frac{G^2(\theta)}{2}$$

where $G^2 = Y^T W Y$, $W = V^{-1} - V^{-1} X (X^T V^{-1} X)^{-1} X^T V^{-1}$.

Universal kriging: Predictor $\hat{Y}_0 = \lambda^T Y$, $\sigma_0^2 = E \{ (Y_0 - \hat{Y}_0)^2 \}$, given by

$$\begin{aligned} \lambda &= w^T V^{-1} + (x_0 - X^T V^{-1} w)^T (X^T V^{-1} X)^{-1} X^T V^{-1}, \\ \sigma_0^2 &= v_0 - w^T V^{-1} w + (x_0 - X^T V^{-1} w)^T (X^T V^{-1} X)^{-1} (x_0 - X^T V^{-1} w). \end{aligned}$$

Bayesian Reformulation of Universal Kriging:

$$\tilde{\psi}(z, Y) = \frac{\int e^{\ell_n(\theta) + Q(\theta)} \psi(z, Y; \theta) d\theta}{\int e^{\ell_n(\theta) + Q(\theta)} d\theta}$$

where $e^{\ell_n(\theta)}$ is the restricted likelihood of θ , $Q(\theta) = \log \pi(\theta)$ and $\psi(z, Y; \theta) = \Phi\left(\frac{z - \lambda^T Y}{\sigma_0}\right)$ or $\frac{1}{\sigma_0} \phi\left(\frac{z - \lambda^T Y}{\sigma_0}\right)$; $\Phi(\cdot)$ is the standard normal c.d.f. and $\phi(\cdot)$ the standard normal density.

Design Criteria

$$V_1 = \sigma_0^2 + \text{tr} \left\{ \mathcal{I}^{-1} \left(\frac{\partial \lambda}{\partial \theta} \right)^T V \left(\frac{\partial \lambda}{\partial \theta} \right) \right\}, \quad V_2 = \left(\frac{\partial \sigma_0^2}{\partial \theta} \right)^T \mathcal{I}^{-1} \left(\frac{\partial \sigma_0^2}{\partial \theta} \right),$$

where \mathcal{I} is the observed information matrix for θ .

Zhu-Stein criterion for design: minimize

$$V_3 = V_1 + \frac{V_2}{2\sigma_0^2}.$$

Quantiles of the Predictive Distribution:

$$z_P(Y; \theta) = \lambda^T Y + \sigma_0 \Phi^{-1}(P), \quad \hat{z}_P(Y) = \hat{\lambda}^T Y + \hat{\sigma}_0 \Phi^{-1}(P), \quad \tilde{z}_P(Y) = \tilde{\psi}^{-1}(P, Y).$$

Likelihood Notation: Define $U_i = \frac{\partial \ell_n(\theta)}{\partial \theta^i}$, $U_{ij} = \frac{\partial^2 \ell_n(\theta)}{\partial \theta^i \partial \theta^j}$, $U_{ijk} = \frac{\partial^3 \ell_n(\theta)}{\partial \theta^i \partial \theta^j \partial \theta^k}$. Other quantities $Q(\theta)$, $\lambda(\theta)$, $\sigma_0(\theta)$. Suffixes denote partial differentiation, for example $Q_i = \partial Q / \partial \theta^i$, $\sigma_{0ij} = \partial^2 \sigma_0 / \partial \theta^i \partial \theta^j$. Let $\kappa_{i,j} = n^{-1} E \{ U_i U_j \}$, $\kappa_{ijk} = n^{-1} E \{ U_{ijk} \}$, $\kappa_{i,jk} = n^{-1} E \{ U_i U_{jk} \}$. Suppose

inverse of $\{\kappa_{i,j}\}$ matrix has entries $\{\kappa^{i,j}\}$. We assume all these quantities are of $O(1)$ as $n \rightarrow \infty$ and we employ the summation convention. Then

$$\begin{aligned}
nE \{ \psi(\hat{z}_P(Y); Y, \theta) - \psi(z_P(Y); Y, \theta) \} &\sim \phi(\Phi^{-1}(P))\Phi^{-1}(P) \left[-\frac{1}{2}\Phi^{-1}(P)^2 \kappa^{i,j} \frac{\sigma_{0i}\sigma_{0j}}{\sigma_0^2} \right. \\
&\quad \left. + \kappa^{i,j} \kappa^{k,\ell} \left(\kappa_{jk,\ell} + \frac{1}{2}\kappa_{jkl} \right) \frac{\sigma_{0i}}{\sigma_0} + \frac{1}{2}\kappa^{i,j} \left\{ \frac{\sigma_{0ij}}{\sigma_0} - \frac{\lambda_i^T V \lambda_j}{\sigma_0^2} \right\} \right. \\
&\quad \left. - \frac{1}{2}\kappa^{i,k} \kappa^{j,\ell} \cdot \frac{1}{n\sigma_0^2} \left(\lambda_i^T V \frac{\partial W}{\partial \theta^k} V \frac{\partial W}{\partial \theta^\ell} V \lambda_j + \lambda_i^T V \frac{\partial W}{\partial \theta^\ell} V \frac{\partial W}{\partial \theta^k} V \lambda_j \right) \right], \\
nE \{ \psi(\tilde{z}_P(Y); Y, \theta) - \psi(z_P(Y); Y, \theta) \} &\sim \phi(\Phi^{-1}(P))\Phi^{-1}(P) \left[\kappa^{i,j} \kappa^{k,\ell} (\kappa_{jk,\ell} + \kappa_{jkl}) \frac{\sigma_{0i}}{\sigma_0} \right. \\
&\quad \left. - \kappa^{i,j} \left(\frac{\sigma_{0i}\sigma_{0j}}{\sigma_0^2} - \frac{\sigma_{0ij}}{\sigma_0} \right) + \kappa^{i,j} \frac{\sigma_{0i}}{\sigma_0} Q_j \right. \\
&\quad \left. - \frac{1}{2}\kappa^{i,k} \kappa^{j,\ell} \cdot \frac{1}{n\sigma_0^2} \left(\lambda_i^T V \frac{\partial W}{\partial \theta^k} V \frac{\partial W}{\partial \theta^\ell} V \lambda_j + \lambda_i^T V \frac{\partial W}{\partial \theta^\ell} V \frac{\partial W}{\partial \theta^k} V \lambda_j \right) \right], \\
nE \{ \hat{z}_P - z_P \} &\approx \Phi^{-1}(P) \left\{ \kappa^{i,j} \kappa^{k,\ell} \sigma_{0\ell} \left(\kappa_{ik,j} + \frac{1}{2}\kappa_{ijk} \right) + \frac{1}{2}\kappa^{i,j} \sigma_{0ij} \right\} \\
nE \{ \tilde{z}_P - z_P \} &\approx \Phi^{-1}(P) \left\{ \kappa^{i,j} \kappa^{k,\ell} \sigma_{0\ell} (\kappa_{ik,j} + \kappa_{ijk}) + \kappa^{i,j} \left(\sigma_{0ij} - \frac{\sigma_{0i}\sigma_{0j}}{\sigma_0} \right) \right. \\
&\quad \left. + \kappa^{i,j} Q_j \sigma_{0i} + \frac{1}{2}\Phi^{-1}(P)^2 \kappa^{i,j} \frac{\sigma_{0i}\sigma_{0j}}{\sigma_0} + \frac{1}{2}\kappa^{i,j} \frac{\lambda_i^T V \lambda_j}{\sigma_0} \right\}.
\end{aligned}$$

An improved estimator for z_P is

$$\begin{aligned}
z_P^\dagger &= \hat{z}_P - n^{-1}\Phi^{-1}(P) \left\{ \hat{\kappa}^{i,j} \hat{\kappa}^{k,\ell} \hat{\sigma}_{0\ell} \left(\hat{\kappa}_{ik,j} + \frac{1}{2}\hat{\kappa}_{ijk} \right) + \frac{1}{2}\hat{\kappa}^{i,j} \left(\hat{\sigma}_{0ij} - \frac{\hat{\sigma}_{0i}\hat{\sigma}_{0j}}{\hat{\sigma}_0} \Phi^{-1}(P)^2 \right) - \frac{1}{2\hat{\sigma}_0} \hat{\kappa}^{i,j} \hat{\lambda}_i^T \hat{V} \hat{\lambda}_j \right. \\
&\quad \left. - \frac{1}{2n\hat{\sigma}_0} \hat{\kappa}^{i,j} \hat{\kappa}^{k,\ell} \left(\hat{\lambda}_j^T \hat{V} \frac{\partial \hat{W}}{\partial \theta^i} \hat{V} \frac{\partial \hat{W}}{\partial \theta^k} \hat{V} \hat{\lambda}_\ell + \hat{\lambda}_j^T \hat{V} \frac{\partial \hat{W}}{\partial \theta^k} \hat{V} \frac{\partial \hat{W}}{\partial \theta^i} \hat{V} \hat{\lambda}_\ell \right) \right\}.
\end{aligned}$$

References

- Smith, R.L. (2004), Asymptotic theory for kriging with estimated parameters and its application to network design. Preliminary version, available from <http://www.stat.unc.edu/postscript/rs/supp5.pdf>
- Zhu, Z. and Stein, M.L. (2004), Two-step spatial sampling design for prediction with estimated parameters. Preprint, University of North Carolina and University of Chicago.